Double Somos-4

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Somos–(4) sequence $\{s_n\}$ is defined by initial data

$$
s_1 = s_2 = s_3 = s_4 = 1
$$

and recurrence relation

$$
s_{n+2}s_{n-2}=s_{n+1}s_{n-1}+s_n^2.
$$

It begings with

 \ldots , 2, 1, 1, 1, 1, 2, 3, 7, 23, 59, 314, 1529, \ldots

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(Obviously $s_n = s_{5-n}$.)

Somos–(6)

Somos first introduced the sequence Somos-(6) such that

$$
s_1=s_2=s_3=s_4=s_5=s_6=1\\
$$

and

$$
s_{n+3}s_{n-3}=s_{n+2}s_{n-2}+s_{n+1}s_{n-1}+s_n^2.
$$

He raised the question whether all the terms are integer:

1470^{*} Proposed by Michael Somos, Cleveland, Ohio. Consider the sequence (a_n) where $a_0 = a_1 = \cdots = a_5 = 1$ and $a_n = \frac{a_{n-1}a_{n-5} + a_{n-2}a_{n-4} + a_{n-3}^2}{a_{n-2}}$

for $n \geq 6$. Computer calculations show that $a_{6}, a_{7}, \ldots, a_{100}$ are all integers. Consequently it is conjectured that all the a_n are integers. Prove or disprove.

Somos M. Problem 1470. Crux Mathematicorum, 15: 7 (1989), p. 208. 200

The integrality of Somos–(4) and Somos–(5) was proved by Janice Malouf, Enrico Bombieri and Dean Hickerson (1990).

The integrality of Somos–(6) was proved by Dean Hickerson (April 1990).

The integrality of Somos–(7) was proved by Ben Lotto (May 1990).

Somos–(8) is a sequence with initial data

$$
\mathsf{s}_1=\mathsf{s}_2=\mathsf{s}_3=\mathsf{s}_4=\mathsf{s}_5=\mathsf{s}_6=\mathsf{s}_7=\mathsf{s}_8=1
$$

satisfying recurrence relation

$$
s_{n+4}s_{n-4}=s_{n+3}s_{n-3}+s_{n+2}s_{n-2}+s_{n+1}s_{n-1}+s_n^2.
$$

Somos–(8) is NOT an integer sequence:

 \ldots , 1, 1, 1, 1, 1, 1, 1, 1, 4, 7, 13, 25, 61, 187, 775, 5827, 14815, $\frac{420514}{7}$ $\frac{1}{7}$, ...

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Definition

For integer $k \geq 4$ Somos– k sequence is a sequence generated by quadratic recurrence relation of the form

$$
\tau_{n+k}\tau_n = \sum_{j=1}^{[k/2]} \alpha_j \tau_{n+k-j}\tau_{n+j},
$$

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where α_i are constants and τ_1, \ldots, τ_k are initial data.

The problem of integrality: how to check the integrality of general Somos–k sequences?

Theorem (Fomin and Zelevinsky, 2002)

For a Somos-k sequences ($k = 4, 5, 6$ and 7) all of the terms in the sequences are Laurent polynomials in these initial data whose coefficients are in $\mathbb{Z}[\alpha_1,\ldots,\alpha_{k/2}]$, so that

$$
\tau_n \in \mathbb{Z}[\alpha_1,\ldots,\alpha_{[k/2]},\tau_1^{\pm 1},\ldots,\tau_k^{\pm 1}] \text{ for all } n \in \mathbb{Z}.
$$

S. Fomin S. and Zelevinsky A. "The Laurent Phenomenon", Adv. Appl. Math. 28 (2002) 119–144.

Integrality of original Somos– (k) sequences follows from the theorem with

$$
\alpha_1=\cdots=\alpha_{[k/2]}=\tau_1=\cdots=\tau_k=1.
$$

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But this Theorem is not a final step.

A stronger version of the Laurent property for Somos–4

Theorem (Hone and Swart, 2008)

Consider a Somos–4 sequence defined by a fourth-order recurrence

$$
\tau_{n+4}\tau_n=\alpha\tau_{n+3}\tau_{n+1}+\beta\tau_n^2
$$

with initial data τ_1 , τ_2 , τ_3 , τ_4 , and translation invariant

$$
T = \frac{\tau_1^2 \tau_4^2 + \alpha (\tau_2^3 \tau_4 + \tau_1 \tau_3^3) + \beta \tau_2^2 \tau_3^2}{\tau_1 \tau_2 \tau_3 \tau_4},
$$

and $I=\alpha^2+\beta\,T$. Then for all $n\geq 1$

$$
\tau_n \in \mathbb{Z}[\alpha,\beta,1,\tau_1^{\pm 1},\tau_2,\tau_3,\tau_4].
$$

Hone A. N., Swart C. Integrality and the Laurent phenomenon for Somos–4 and Somos–5 sequences. Math. Proc. Camb. Philos. Soc., Cambridge University Press, Cambridge, 20[08](#page-6-0), [1](#page-8-0)[45](#page-6-0)[,](#page-7-0) [65](#page-8-0)[–8](#page-0-0)[5.](#page-0-1)

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By definition

$$
\sigma_{\Gamma}(z) = z \prod_{w \in \Gamma \setminus \{0\}} \left(1 - \frac{z}{w}\right) e^{\frac{z}{w} + \frac{1}{2}(\frac{z}{w})^2}
$$

– Weierstrass sigma-function associated to lattice Γ. In degenerate cases:

1) for
$$
\Gamma = \{0\}
$$
 $\sigma_{\Gamma}(z) = z$;
\n2) for $\Gamma = \{mw|m \in \mathbb{Z}\}\$ with $w \in \mathbb{C}\setminus\{0\}$
\n
$$
\sigma_{\Gamma}(z) = z \prod_{n \in \mathbb{Z}\setminus\{0\}} \left(1 - \frac{z}{nw}\right) e^{\frac{z}{nw} + \frac{1}{2}(\frac{z}{nw})^2} = \frac{w}{\pi} \sin \frac{\pi z}{w} e^{\frac{\pi^2}{6}(\frac{z}{w})^2}.
$$

Sigma-function is odd entire function with simple zeros at the points of lattice Γ.

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Theorem (Hone and Swart, 2003–2005)

The general solution of recurrence relation

$$
\tau_{n+2}\tau_{n-2} = \alpha \tau_{n+1}\tau_{n-1} + \beta \tau_n^2
$$

for $\alpha \neq 0$ takes the form

$$
\tau_n = CD^n \frac{\sigma(z_0 + nz)}{\sigma(z)^{n^2}},
$$

where z, $z_0 \in \mathbb{C}^*$, $C = \frac{\tau_0}{\sigma(z)}$ $\frac{\tau_0}{\sigma(z_0)},\ D=\frac{\sigma(z)\sigma(z_0)\tau_1}{\sigma(z+z_0)\tau_0}$ $\frac{\sigma(z)\sigma(z_0)\tau_1}{\sigma(z+z_0)\tau_0}$.

- A. Hone, Elliptic Curves and Quadratic Recurrence Sequences Bull. Lon, Math. Soc. 37 2 (2005) 161–171.
- \blacksquare C. Swart *Elliptic curves and related sequences*, PhD thesis, Royal Holloway, University of London (2[00](#page-9-0)[3\).](#page-11-0)

Consider a Double Somos–4 sequence which is a sequence of couples $(A_n, B_n) \subset \mathbb{C}^2$ defined by initial data

$$
A_{\pm 2}, A_{\pm 1}, A_0, B_{\pm 2}, B_{\pm 1}, B_0
$$

and a fourth-order recurrences

$$
A_{n+2}B_{n-2} = \alpha A_{n+1}B_{n-1} + \beta A_n B_n,
$$

$$
A_{n-2}B_{n+2} = \gamma A_{n-1}B_{n+1} + \delta A_n B_n.
$$

Here coefficients α , β , γ , δ are NOT arbitrary. They are some functions of initial data. For example fourth-order recurrences then for $n = 0$ give linear equation on α , β , γ , δ .

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Theorem (Bykovskii and Ustinov, 2015)

The general solution of recurrence relations

$$
A_{n+2}B_{n-2} = \alpha A_{n+1}B_{n-1} + \beta A_n B_n,
$$

$$
A_{n-2}B_{n+2} = \gamma A_{n-1}B_{n+1} + \delta A_n B_n.
$$

(subject to some natural restrictions on initial data) takes the form

$$
A_n = C_1 D_1^n \frac{\sigma(z_1 + nz)}{\sigma(z)^{n^2}}, \qquad B_n = C_2 D_2^n \frac{\sigma(z_2 + nz)}{\sigma(z)^{n^2}},
$$

where $z, z_1, z_2 \in \mathbb{C}^*$,

$$
C_1 = \frac{A_0}{\sigma(z_1)}, \quad D_1 = \frac{\sigma(z)\sigma(z_1)A_1}{\sigma(z+z_1)A_0}, \quad C_2 = \frac{B_0}{\sigma(z_2)}, \quad D_2 = \dots
$$

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General Somos–4 (and Somos–5) sequence satisfy "magic determinant property" (Ma, 2010)

$$
\begin{vmatrix} \tau_{m_1+n_1} \tau_{m_1-n_1} & \tau_{m_1+n_2} \tau_{m_1-n_2} & \tau_{m_1+n_3} \tau_{m_1-n_3} \\ \tau_{m_2+n_1} \tau_{m_2-n_1} & \tau_{m_2+n_2} \tau_{m_2-n_2} & \tau_{m_2+n_3} \tau_{m_2-n_3} \\ \tau_{m_3+n_1} \tau_{m_3-n_1} & \tau_{m_3+n_2} \tau_{m_3-n_2} & \tau_{m_3+n_3} \tau_{m_3-n_3} \end{vmatrix} = 0,
$$

where m_i , n_i $(i=1,2,3)$ are arbitrary integers or half-integers. Sequences $\{A_n\}$, $\{B_n\}$ from the Theorem satisfy similar conditions:

$$
\begin{vmatrix} A_{m_1+n_1}B_{m_1-n_1} & A_{m_1+n_2}B_{m_1-n_2} & A_{m_1+n_3}B_{m_1-n_3} \ A_{m_2+n_1}B_{m_2-n_1} & A_{m_2+n_2}B_{m_2-n_2} & A_{m_2+n_3}B_{m_2-n_3} \ A_{m_3+n_1}B_{m_3-n_1} & A_{m_3+n_2}B_{m_3-n_2} & A_{m_3+n_3}B_{m_3-n_3} \ \end{vmatrix} = 0.
$$

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We'll use only 3 of them as assumptions.

The natural restrictions are:

For initial data

$$
\begin{vmatrix} A_2B_0 & A_1B_1 & A_0B_2 \ A_1B_{-1} & A_0B_0 & A_{-1}B_1 \ A_0B_{-2} & A_{-1}B_{-1} & A_{-2}B_0 \end{vmatrix} = 0,
$$

for A_3

$$
\begin{vmatrix} A_3B_0 & A_2B_1 & A_1B_2 \ A_2B_{-1} & A_1B_0 & A_0B_1 \ A_1B_{-2} & A_0B_{-1} & A_{-1}B_0 \end{vmatrix} = 0,
$$

and for B_3

$$
\begin{vmatrix} A_2B_1 & A_1B_2 & A_0B_3 \ A_1B_0 & A_0B_1 & A_{-1}B_2 \ A_0B_{-1} & A_{-1}B_0 & A_{-2}B_1 \end{vmatrix} = 0.
$$

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If A_3 and B_3 are given then α , β are uniquely defined by equations

$$
A_{n+2}B_{n-2} = \alpha A_{n+1}B_{n-1} + \beta A_n B_n \qquad (n = 0, 1)
$$

and γ , δ are uniquely defined by equations

$$
A_{n-2}B_{n+2} = \gamma A_{n-1}B_{n+1} + \delta A_n B_n \qquad (n = 0, 1).
$$

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The Laurent property for Double Somos–4

We have

$$
\begin{vmatrix} A_{2n}B_0 & A_{n+1}B_{n-1} & A_nB_n \ A_{1+n}B_{1-n} & A_2B_0 & A_1B_1 \ A_nB_{-n} & A_1B_{-1} & A_0B_0 \ \end{vmatrix} = \begin{vmatrix} A_{2n-1}B_0 & A_nB_{n-1} & A_{n-1}B_n \ A_nB_{1-n} & A_1B_0 & A_0B_1 \ A_{n-1}B_{-n} & A_0B_{-1} & A_{-1}B_0 \ \end{vmatrix} = 0,
$$

and the same for B_{2n} , B_{2n-1} .

Theorem (Bykovskii and Ustinov, 2015)

$$
A_n, B_n \in \mathbb{Z}[A_0^{\pm 1}, B_0^{\pm 1}, A_{\pm 1}, A_{\pm 2}, B_{\pm 1}, B_{\pm 2}, \Delta_0^{\pm 1}, \Delta_1^{\pm 1}, \Delta_2^{\pm 1}],
$$

where

$$
\Delta_0 = \begin{vmatrix} A_1 B_0 & A_0 B_1 \\ A_0 B_{-1} & A_{-1} B_0 \end{vmatrix}, \quad \Delta_1 = \begin{vmatrix} A_2 B_0 & A_1 B_1 \\ A_1 B_{-1} & A_0 B_0 \end{vmatrix},
$$

$$
\Delta_2 = \begin{vmatrix} A_0 B_2 & A_1 B_1 \\ A_{-1} B_1 & A_0 B_0 \end{vmatrix}.
$$

Questions?

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